# Hear The Flow: Optical Flow-Based Self-Supervised Visual Sound Source Localization

Dennis Fedorishin\*, Deen Dayal Mohan\*, Bhavin Jawade, Srirangaraj Setlur, Venu Govindaraju

University at Buffalo, Buffalo, New York, USA



## Abstract

Learning to localize the sound source in videos without explicit annotations is a novel area of audio-visual research. Existing work in this area focuses on creating attention maps to capture the correlation between the two modalities to localize the source of the sound. In a video, oftentimes, the objects exhibiting movement are the ones generating the sound. In this work, we capture this characteristic by modeling the optical flow in a video as a prior to better aid in localizing the sound source. We further demonstrate that the addition of flow-based attention substantially improves visual sound source localization. Finally, we benchmark our method on standard sound source localization state-of-the-art achieve datasets and performance on the SoundNet Flickr and VGG Sound Source datasets



Method	Training Set	$cIoU_{0.5}$	$AUC_{cIoU}$
Attention [28]	VGGSound 10k	0.160	0.283
LVS* [6]		0.297	0.358
SSPL [30]		0.314	0.369
HTF (Ours)		0.393	0.398
Attention [28]		0.185	0.302
AVObject [1]		0.297	0.357
LVS* [6]		0.301	0.361
LVS <sup>†</sup> [6]	VGGSound 144k	0.288	0.359
HardPos [29]		0.346	0.380
SSPL [30]		0.339	0.380
HTF (Ours)		0.394	0.400



#### LOCALIZATION

 Localization using similarity of audio features at each visual spatial location



Construct positive and negative regions across samples in a batch and train with contrastive loss, like InfoNCE

$$\operatorname{Pos}_{k} = \frac{1}{|PM_{k}^{p}|} \langle PM_{k}^{p}, S_{k \to k} \rangle$$
$$\operatorname{Neg}_{k} = \frac{1}{|I|} \langle 1 - PM_{k}^{n}, S_{k \to k} \rangle$$

Strong ability to generalize across datasets

and unheard sound classes

Method	Testing Set	$cIoU_{0.5}$	$AUC_{cIoU}$
LVS* [6]	VGGSS Heard 110	0.251	0.336
HTF (Ours)		0.373	0.386
LVS* [6]	VGGSS Unheard 110	0.270	0.349
HTF (Ours)		0.393	0.400



The proposed OFLN generalizes well even in

# **Background & Motivation**

#### **VISUAL SOUND SOURCE LOCALIZATION**

Given a video or image frame, localize the dominant sounding object(s)

#### CHALLENGES

- Supervised methods require costly manually-labeled bounding boxes of sounding objects
- Creating audio-visual associations for localizing in a self-supervised settings is challenging

#### **MOTIVATION**

- Recent works focus on new loss formulations for improving contrastive representation learning
- We show the importance of *informative*

#### **OPTICAL FLOW CROSS-ATTENTION**

Construct similarity matrix of visual and optical flow feature representations



- Create cross-attended visual and optical flow features
  - $E = V_v^{ij} \beta^{ij}; \forall i \in [1, m]; \forall j \in [1, n]$
- Add attended flow features to visual feature map and construct *enhanced* similarity map of audio features at each
  - visual-flow spatial location

 $f_{enh} = f_v \oplus E_p$ 



### Results

- State-of-the-art performance on Flickr SoundNet and VGG Sound Source testing datasets
- Using loss functions from previous works, we show incorporating optical flow significantly improves VSSL.

Method	Training Set	$cIoU_{0.5}$	$AUC_{cIoU}$
Attention [28]	Flickr 10k	0.436	0.449
CoarseToFine [25]		0.522	0.496
AVObject [1]		0.546	0.504
LVS* [6]		0.730	0.578
SSPL [30]		0.743	0.587
HTF (Ours)		0.860	0.634
Attention [28]	Flickr 144k	0.660	0.558
DMC [19]		0.671	0.568
LVS* [6]		0.702	0.588
LVS† [6]		0.697	0.560
HardPos [29]		0.762	0.597
SSPL [30]		0.759	0.610
HTF (Ours)		0.865	0.639
LVS* [6]	VGGSound 144k	0.719	0.587
HardPos [29]		0.768	0.592
SSPL [30]		0.767	0.605
HTF (Ours)		0.848	0.640

#### the absence of meaningful optical flow



# Conclusion

- We explore and usefulness of *informative* priors to train self-supervised visual sound source localization models
- We incorporate optical flow with our novel OFLN, achieving **state-of-the-art results**

*priors,* like optical flow, to improve VSSL with existing losses

# Method

- In a video, oftentimes the objects that are moving are making sounds.
- We model this characteristic with our *Optical* Flow Localization Network (OFLN)



#### **SELF-SUPERVISED TRAINING**

Threshold the similarity matrix into positive and negative pseudo masks

 $\mathrm{PM}_{k}^{p} = \sigma(S_{k \to k} - \epsilon_{p})/\tau$  $PM_k^n = \sigma(S_{k \to k} - \epsilon_n)/\tau$ 

#### across all VSSL benchmarks

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#### REFERENCES

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# dcfedori@buffalo.edu

Download our code: https://github.com/denfed/heartheflow